

# Opérateurs vectoriels

⊗ Gradient → dérivée en 3D.

$\vec{\nabla}(\cdot) = \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{pmatrix}$   
 ↙  
 chp scalaire

$\vec{\nabla}(\cdot) = \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{1}{r} \frac{\partial}{\partial r} \\ \frac{\partial}{\partial z} \end{pmatrix}$

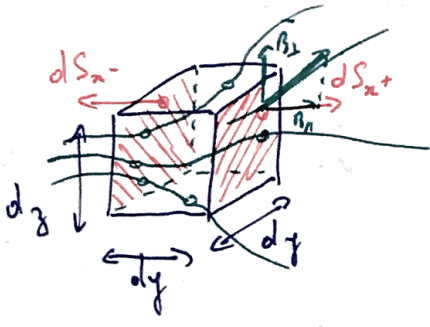
$\vec{\nabla}(\cdot) = \begin{pmatrix} \frac{\partial}{\partial r} \\ \frac{1}{r} \frac{\partial}{\partial \theta} \\ \frac{1}{r \sin(\theta)} \frac{\partial}{\partial \varphi} \end{pmatrix}$

idée:  $\frac{d}{d\vec{r}}$

⊗ Divergence:

élémentaire  
flux par unité de volume à travers un élément de volume  $d\tau$ .

Convention: positif si sortant

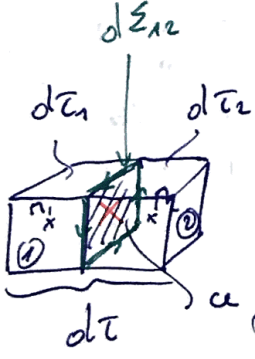


$d\phi = +B_n(x+dx, y, z) \cdot dy \cdot dz - B_n(x, y, z) \cdot dy \cdot dz + \text{idem } y, z$   
 $= + \frac{\partial B_n}{\partial x} \cdot dx \cdot dy \cdot dz + \frac{\partial B_y}{\partial y} d\tau + \frac{\partial B_z}{\partial z} d\tau$

$d\phi = \text{Div}(\vec{B}) d\tau$

avec  $\text{Div}(\vec{B}) = \frac{\partial B_x}{\partial x} + \frac{\partial B_y}{\partial y} + \frac{\partial B_z}{\partial z}$

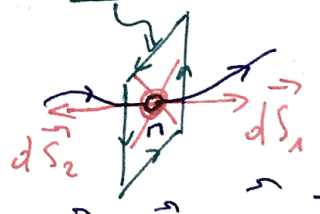
Csq:



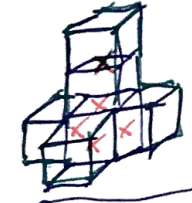
ce qui sort de ① rentre dans ②.  $\vec{e}$  travers  $d\xi_{12}$

Soit  $d^3\phi = d^3\phi_1 + d^3\phi_2$

$d^3\phi = \text{Div}(\vec{B})(n_1) d\tau(n_1) + \text{Div}(\vec{B})(n_2) d\tau(n_2)$

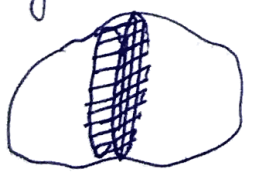


$0 = \vec{B}(n_1) \cdot d\vec{S}_1 + \vec{B}(n_2) \cdot d\vec{S}_2$



$d\phi_{\text{tot}} = \sum_n d\phi_n$

Globalement



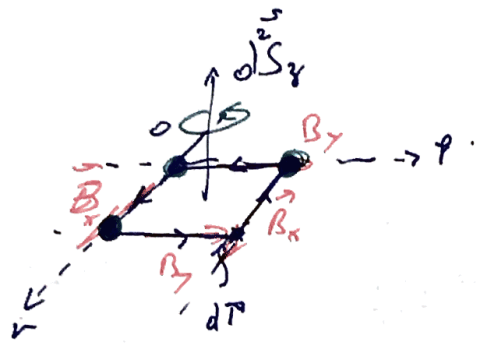
$\phi = \oint \vec{B} \cdot d\vec{S} = \iiint d^3\phi = \iiint \text{Div}(\vec{B})(n) d\tau(n)$

Soit  $\oint \vec{B} \cdot d\vec{S} = \iiint \text{Div}(\vec{B}) d\tau$

Green - Ostrogradsky.

\* Opérateur Rotationnel:

\* Circulation élémentaire par unité de Surface.



ici cas 2D

$$C = \oint \vec{B} \cdot d\vec{l} \text{ circulation}$$

$$dC_z = B_x(n, y, z) \cdot dx + B_y(n, x, y, z) \cdot dy - B_y(n, x, y, z) \cdot dy - B_x(n, x, y, z) \cdot dx$$

Soit  $dC_z = -\frac{\partial B_x}{\partial y} dy \cdot dx + \frac{\partial B_y}{\partial x} dx \cdot dy = \left[ \frac{\partial B_y}{\partial x} - \frac{\partial B_x}{\partial y} \right] \cdot dS_z$

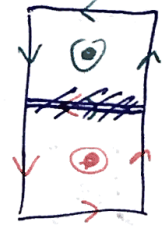
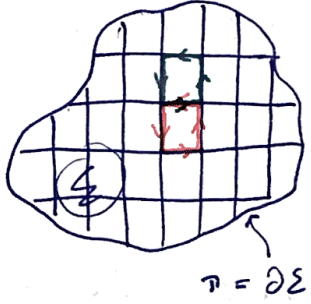
$dC_z = \text{Rot}(\vec{B}) \cdot dS_z$

Cas général 3D

$$\vec{\text{Rot}}(\vec{B}) = \begin{pmatrix} \frac{\partial B_z}{\partial y} - \frac{\partial B_y}{\partial z} \\ \frac{\partial B_x}{\partial z} - \frac{\partial B_z}{\partial x} \\ \frac{\partial B_y}{\partial x} - \frac{\partial B_x}{\partial y} \end{pmatrix}$$

$$\vec{\text{Rot}}(\vec{B}) = \vec{\nabla} \wedge \vec{B} = \begin{vmatrix} \vec{e}_1 & \vec{e}_2 & \vec{e}_3 \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ B_x & B_y & B_z \end{vmatrix}$$

Comptance en 2D



$$dC_{1+2} = dC_1 + dC_2$$

$$\oint_{\gamma} \vec{B} \cdot d\vec{l} = \iint_{\Sigma} dC_n = \iint_{\Sigma} \vec{\text{Rot}}(\vec{B}) \cdot d\vec{S}_n$$

$$\oint_{\gamma} \vec{B} \cdot d\vec{l} = \iint_{\Sigma} \vec{\text{Rot}}(\vec{B}) \cdot d\vec{S}$$

Formule de Stokes

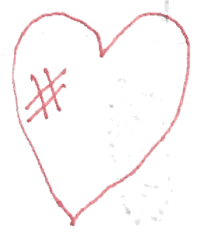
Conclusion  $\mathbb{O}_2 \mathbb{R}$

$\vec{\nabla}()$  : Dérivée 3D

(scalaire)  $\rightarrow$  (Vecteur)

$\text{Div}()$  : flux elem / unite volume (Vect)  $\rightarrow$  (scalaire)

$\text{Rot}()$  : Circulation elem / unite surface (chp. vect)  $\rightarrow$  (chp. vect)



Écriture locale des eq<sup>s</sup> de l'électromagnétisme:

eq<sup>s</sup> de Maxwell

$$\left. \begin{array}{l} \text{NF} \\ \text{NT} \\ \text{NF} \\ \text{NA} \end{array} \right\} \begin{array}{l} \text{Div}(\vec{E}) = \frac{\rho}{\epsilon_0} \\ \text{Div}(\vec{B}) = 0 \\ \text{Rot}(\vec{E}) = -\frac{\partial \vec{B}}{\partial t} \\ \text{Rot}(\vec{B}) = \mu_0 \vec{j} + \underbrace{\left( \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right)}_{\text{Terme de Maxwell}} \end{array} \quad \left. \begin{array}{l} \text{sans de charge} \\ \\ \\ \text{sans de courant} \end{array} \right\} \text{géométriques.}$$

\*  $\vec{B}$  flux conservatif:

$$\forall \Sigma \text{ fermée} \quad \oint_{\Sigma} \vec{B} \cdot d\vec{S} = 0 \quad : \quad \iiint_V \text{Div}(\vec{B}) \cdot dt \quad \forall V \Rightarrow \boxed{\text{Div}(\vec{B}) = 0}$$

\* Loi de Faraday:

$$e = -\frac{d\phi}{dt} \quad \text{avec} \quad e = \oint_{\Gamma} \vec{E} \cdot d\vec{l} \quad \text{et} \quad \phi = \iint_{\Sigma} \vec{B} \cdot d\vec{S}$$

$$\text{Soit } e = \oint_{\Gamma} \vec{E} \cdot d\vec{l} = \iint_{\Sigma} \text{Rot}(\vec{E}) \cdot d\vec{S} = -\frac{d}{dt} \iint_{\Sigma} \vec{B} \cdot d\vec{S} = \iint_{\Sigma} -\frac{\partial \vec{B}}{\partial t} \cdot d\vec{S} \quad \left[ \iint_{\Sigma} (\text{Rot} \vec{E} + \frac{\partial \vec{B}}{\partial t}) \cdot d\vec{S} = 0 \right] \quad \forall \Sigma$$

Soit  $\boxed{\text{Rot}(\vec{E}) = -\frac{\partial \vec{B}}{\partial t}}$

$\Sigma$  fixe de la temp  $\Rightarrow$  Circuit fixe.

charge de  $V$

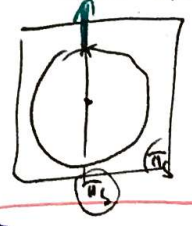
\* Th de Gauss:

$$\iiint_V \text{Div}(\vec{E}) \cdot dt = \iiint_V \frac{\rho}{\epsilon_0} \cdot dt = \frac{\iiint_V \rho \cdot dt}{\epsilon_0} = \frac{Q}{\epsilon_0}$$

$\boxed{\oint_{\Sigma} \vec{E} \cdot d\vec{S} = \frac{Q_V}{\epsilon_0}}$

est: charge ponctuelle.

$$r \sim E_r(r) = \frac{q}{\epsilon_0} \quad \left[ E_r(r) = \frac{q}{4\pi \epsilon_0 r^2} \right]$$

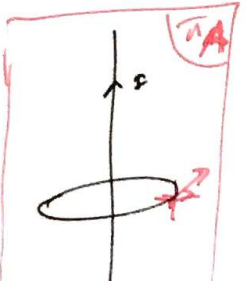


entouré par  $\Gamma$ .

\* Th d'Ampère:

Hypothèse statique  $\left( \frac{\partial \vec{E}}{\partial t} = 0 \right)$

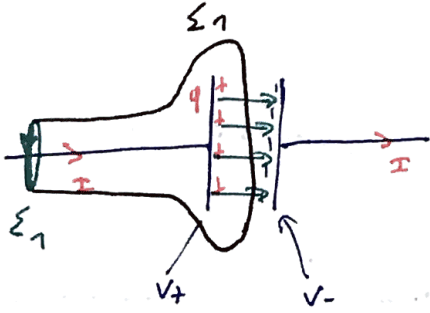
$$\iint_{\Sigma} \text{Rot}(\vec{B}) \cdot d\vec{S} = \mu_0 \iint_{\Sigma} \vec{j} \cdot d\vec{S} \quad \text{Soit} \quad \boxed{\oint_{\Gamma} \vec{B} \cdot d\vec{l} = \mu_0 I}$$



$r \sim B_0 = \mu_0 I$

$$\boxed{B_0(r) = \frac{\mu_0 I}{2\pi r}}$$

# Le Terme de Maxwell



$$\text{rot}(\vec{B}) = \mu_0 \vec{j} + \left( \epsilon_0 \mu_0 \frac{\partial \vec{E}}{\partial t} \right)$$

$$\textcircled{\epsilon_1} \oint_{\Gamma_1} \vec{B} \cdot d\vec{l} = \iint_{\Sigma_1} \text{rot}(\vec{B}) \cdot d\vec{S} = \mu_0 \iint_{\Sigma_1} \vec{j} \cdot d\vec{S} + \mu_0 \epsilon_0 \frac{\partial}{\partial t} \iint_{\Sigma_1} \vec{E} \cdot d\vec{S}$$

$$\boxed{C_{T_1} = \mu_0 I} \quad \checkmark$$

$$\textcircled{\epsilon_2} \oint_{\Gamma_2} \vec{B} \cdot d\vec{l} = \mu_0 \iint_{\Sigma_2} \vec{j} \cdot d\vec{S} = \mu_0 \iint_{\Sigma_2} \vec{E} \cdot d\vec{S} \approx \mu_0 \epsilon_0 \frac{\partial \Phi}{\partial t} \quad \checkmark$$

① et ② :  $C_{T_1} = \mu_0 I = \mu_0 \epsilon_0 S \cdot \frac{dE}{dt}$  (uniforme)  $\left\{ \begin{array}{l} \vec{E} = -\vec{\nabla}V \\ E = +\frac{U_c}{e} = \frac{q}{ce} \end{array} \right.$

Soit  $\mu_0 \cdot I = \mu_0 \frac{A_0 S}{ce} \frac{dq}{dt}$  or  $C = \frac{\epsilon_0 S}{e}$

$$\boxed{I = \frac{dq}{dt}}$$

\* the Ampère



\* the Gauss

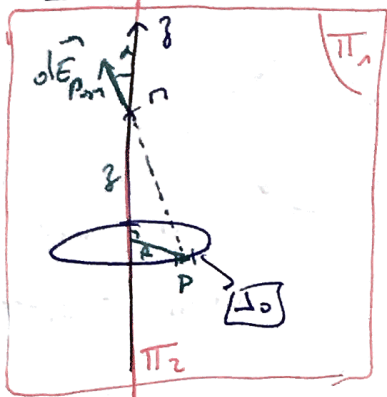


\*  $B_z(B)$  solénoïde  $\infty$  + the Ampère solénoïde



# Symétries et calcul de champ.

① Champ  $E$ :



$$d\vec{E}_{P \rightarrow n} = \frac{dq_p}{4\pi\epsilon_0} \cdot \frac{\vec{r}}{\|\vec{r}\|^3}$$

Loi de Coulomb  

$$\vec{E}_p = \frac{q}{4\pi\epsilon_0} \frac{\vec{r}}{\|\vec{r}\|^3}$$

ici  $dl = \frac{1}{\sin\theta} R d\theta$

$$\vec{E}(z) = \int_{\Gamma} d\vec{E}_{P \rightarrow n} \quad r = \sqrt{R^2 + z^2}$$

Symétries:  $\Pi_1$  et  $\Pi_2$  plans de symétrie du champ  $\Rightarrow \vec{E}(r) \in \Pi_1$  et  $\Pi_2$

$\Rightarrow$  Structure de champ  $\vec{E}(z) = E(z) \vec{e}_z$  selon  $\vec{e}_z$

$$E_z(z) = \vec{E}_z(z) \cdot \vec{e}_z = \int_{\Gamma} \frac{\lambda_0 R d\theta}{4\pi\epsilon_0} \cdot \frac{\vec{r} \cdot \vec{e}_z}{r^3} = \frac{\lambda_0 R}{4\pi\epsilon_0} \frac{z}{\sqrt{R^2 + z^2}^3} \int_0^{2\pi} d\theta$$

$$\vec{E}_z(z) = \frac{Q_{tot}}{4\pi\epsilon_0} \cdot \frac{z}{[R^2 + z^2]^{3/2}} \quad (\vec{E}_z = E_z(z) \vec{e}_z)$$

$(V_2 R)$  Si  $z \rightarrow \infty \quad E_z \rightarrow \frac{Q_{tot}}{4\pi\epsilon_0} \cdot \frac{1}{z^2}$  ✓

$\frac{R_0}{z}$ :  $V = \int \frac{dq_p}{4\pi\epsilon_0} \cdot \frac{1}{r}$  car  $V = \frac{q}{4\pi\epsilon_0} \cdot \frac{1}{r}$  charge ponctuelle.  $V(z) \sim \frac{Q_{tot}}{4\pi\epsilon_0} \cdot \frac{1}{z}$

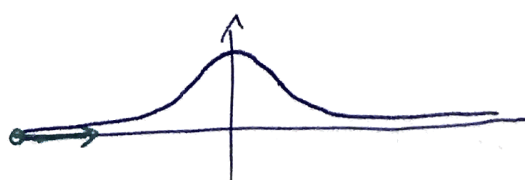
Soit  $V(z) = \int_0^{2\pi} \frac{\lambda_0 R d\theta}{4\pi\epsilon_0} \cdot \frac{1}{\sqrt{R^2 + z^2}} = \frac{Q_{tot}}{4\pi\epsilon_0} \cdot \frac{1}{\sqrt{R^2 + z^2}} = V(z)$

Autre approche.

$$\vec{E} = -\vec{\nabla}(V) = -\frac{\partial V}{\partial z} = \frac{Q_{tot}}{4\pi\epsilon_0} \cdot \frac{z}{[R^2 + z^2]^{3/2}} = \frac{Q_{tot}}{4\pi\epsilon_0} \cdot \frac{z}{[R^2 + z^2]^{3/2}}$$

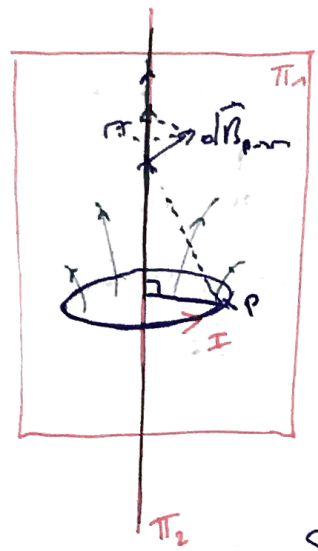
$E_p$ :  $E_p = qV$

$$E_p = \frac{q Q_{tot}}{4\pi\epsilon_0} \cdot \frac{1}{\sqrt{R^2 + z^2}}$$



Vitesse pour traverser l'anneau  $\rightarrow$  B.C.  
 $E_c = E_p^{max} = \frac{q Q_{tot}}{4\pi\epsilon_0} \cdot \frac{1}{R}$

② Champs magnétiques: Loi de Biot & Savart.



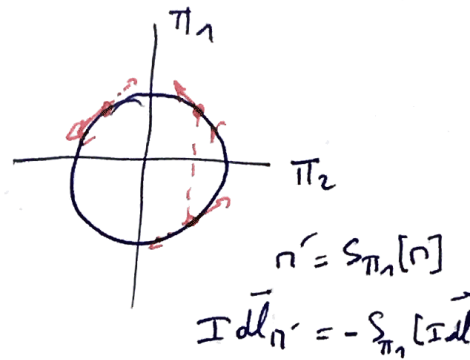
$$\vec{B}(r) = \int \frac{\mu_0}{4\pi} \cdot \frac{I d\vec{l} \wedge \vec{P}\vec{P}'}{\|\vec{P}\vec{P}'\|^3}$$

$\pi_1$  et  $\pi_2$  plan d'antisymétrie

$B(r) \in \pi_1 \wedge \pi_2 \Rightarrow$  selon  $\vec{e}_z$ .

$$\vec{B}(r) = B_z(z) \vec{e}_z$$

Soit  $B_z(z) = \frac{\mu_0}{4\pi} \int_0^{2\pi} \frac{I dl \wedge \vec{P}\vec{P}'}{r^3} \cdot \vec{e}_z$



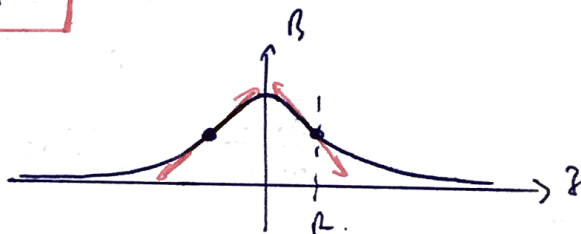
$r' = \sin \theta [r]$   
 $I d\vec{l}' = -\sin \theta [I dl]$

$I d\vec{l}' = I R d\theta \vec{e}_\theta$

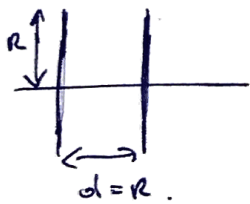
$$B_z(z) = \frac{\mu_0 I}{4\pi} \int_0^{2\pi} \frac{[\vec{e}_z \wedge (R d\theta \vec{e}_\theta)] \cdot \vec{P}\vec{P}'}{r^3} = \frac{\mu_0 R I}{4\pi} \frac{1}{r^3} \int_0^{2\pi} \underbrace{\vec{e}_z \wedge \vec{e}_\theta}_{-\vec{e}_r} \cdot \vec{P}\vec{P}' d\theta$$

$-\vec{e}_r \cdot \vec{P}\vec{P}' = R \quad \vec{P}\vec{P}' \Big|_{-R}^{+R}$

$$B_z(z) = \frac{\mu_0 \cdot \cancel{2\pi} R^2 \cdot I}{\cancel{2\pi} 4\pi} \frac{1}{(\sqrt{R^2+z^2})^3} = \frac{\mu_0 I}{R [1 + (\frac{z}{R})^2]^{\frac{3}{2}}}$$



Bobine de Helmholtz



Conclusion Squarique

Champ  $\vec{E} \begin{cases} \in \pi_S \text{ charge} \\ \perp \pi_{AS} \text{ ligne} \end{cases}$

Chp  $\vec{B} \begin{cases} \in \pi_{AS} \text{ courbe} \\ \perp \pi_S \text{ courbe} \end{cases}$

